Harbor Pursuit

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RWTH Aachen University

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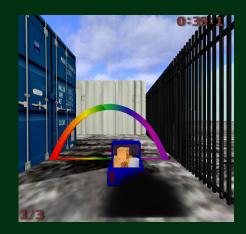


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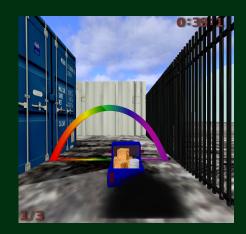




- Time challenge race
- Checkpoint based
- Reset mechanism it player gets stuck
- Chase cam perspective
- Obstacles such as spilled of or chicanes



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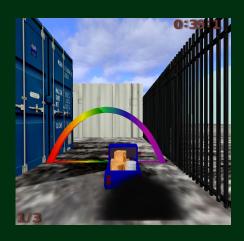


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- Turning Wheels
- Speed Softcap
- Adjusted Camera
- Different Undergrounds





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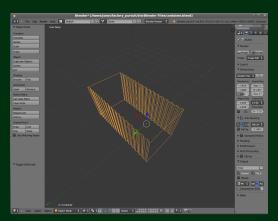
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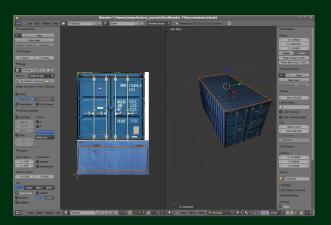
Mesh Modeling

All models are created using Blender 2.63



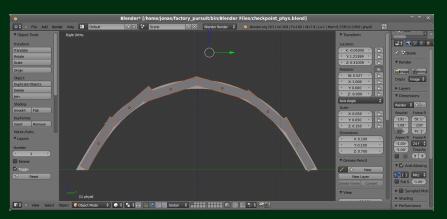
Texturing

UV Textures are also defined in Blender and then exported



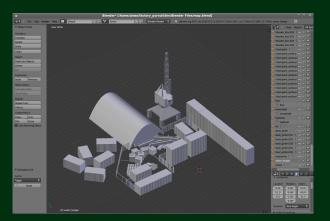
Physical representation

A Python script is used to export basic physical shape of an object



Map creation

The map is put together in Blender and exported using a script





File Format: XML

The Objects properties:



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The whole map:

```
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```

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- set start/end rotation as quaternion
- triangular function interpolates linear betweer quaternions



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- Billboard
- Emitter
- Color, rotation, scaling
- Randomize direction
- Car speed
- Different alpha channels





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- RGB texture
- Downscaled
 and blurred
 multiple times
- Added to HDR texture





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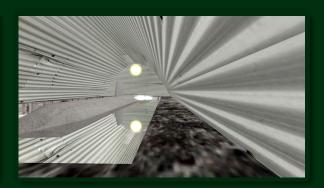
Tone Mapping

- When entering a dark room, the scene appears dark
- It slowly brightens up, as the eye adapts



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Shadow Mapping

- Basic shadow mapping
- Calculated in real time





Shadow Mapping

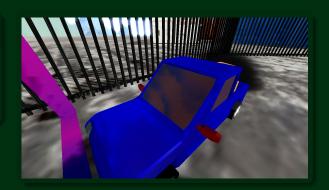
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Environment Mapping

 The skybox is reflected in the paint and glass of the car





Reflection

 The water surface reflects the scene in real time





Debug Drawing

- There are two modes for debugging physics:



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 - Show non-culled wireframes
 - Show all wirefram



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